

Advanced Topics in Geometry A1 (MTH.B405)

Integrability Conditions

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2025/05/09

Problem 2-1

Logistic equation

Problem (Ex. 2-1)

(limit case of SIR-model)

Find the maximal solution of the initial value problem

$$\bullet \quad \frac{dx}{dt} = x(1 - x), \quad x(0) = a,$$

where a is a real number.

• When $a = 0, 1$, $\begin{cases} x(t) = 0 \\ x(t) = 1 \end{cases}$: are solutions

When $a \in \mathbb{R} \setminus \{0, 1\}$

$$\frac{1}{x(1-x)} \frac{dx}{dt} = 1 \quad x(0) = a$$

($\neq 0$ near $t=0$) $\int_0^t dt$

$$\int_0^t \frac{1}{x(1-x)} \frac{dx}{dt} dt = t$$
$$= \int_{x(0)}^{x(t)} \frac{1}{x(1-x)} dx = \left[\log \left| \frac{x}{1-x} \right| \right]_a^{x(t)}$$

$$= \log \left(\underbrace{\frac{x}{1-x}}_{\text{same sign near } t=0} \underbrace{\frac{1-a}{a}}_{\text{same sign near } t=0} \right)$$

The logistic equation

$$x' = x(1-x),$$

$$x(0) = a$$

The Solution:

$$x(t) = \frac{1}{1 + \frac{1-a}{a} e^{-t}}$$

When $a \in (0, 1)$

x is defined on $\mathbb{R}$,

When $a > 1$

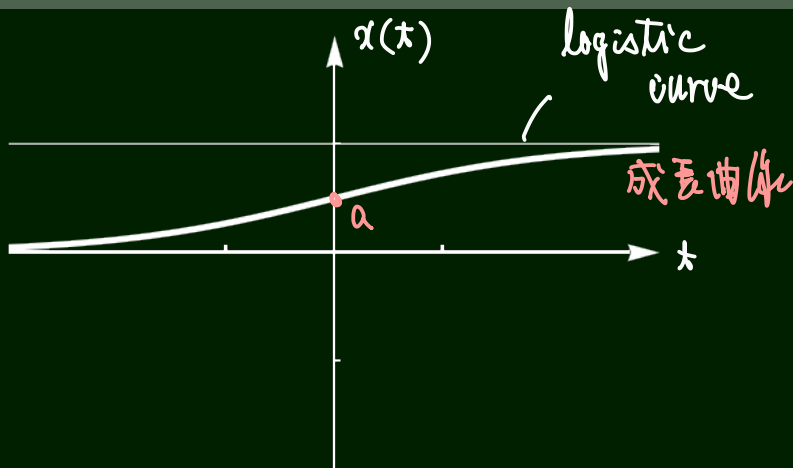
$x(t) \rightarrow$

$a < 0$

$$: \lim_{t \rightarrow \infty} \frac{a-1}{a} < t < +\infty$$

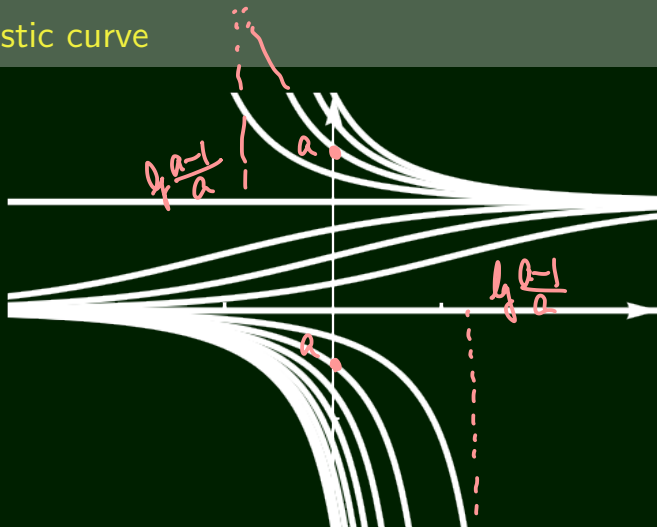
$$: -\infty < t < \lim_{t \rightarrow -\infty} \frac{a-1}{a}$$

The logistic curve



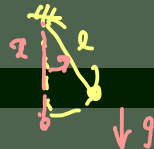
$$x(t) = \frac{1}{1 + \frac{1-a}{a}e^{-t}} \quad (a \in (0, 1))$$

The logistic curve



Exercise 2-2

pendulum



Problem (Ex. 2-2)

Let $x = x(t)$ be the maximal solution of an initial value problem of differential equation

$$\bullet \quad \frac{d^2 x}{dt^2} = -\sin x, \quad x(0) = 0, \quad \frac{dx}{dt}(0) = 2.$$

► Show that $\frac{dx}{dt} = 2 \cos \frac{x}{2}$.

► Verify that x is defined on $\mathbb{R}$, and compute $\lim_{t \rightarrow \pm\infty} x(t)$.

Note The only solution of eq. of pendulum in 'elementary functions'

$$\frac{dx}{dt} \frac{d^2x}{dt^2} = -\sin x \frac{dx}{dt} \quad \Rightarrow \quad \frac{1}{2} \frac{d}{dt} \left(\frac{dx}{dt} \right)^2 = \frac{d}{dt} \cos x$$

$$\frac{d}{dt} \left(\frac{1}{2} \left(\frac{dx}{dt} \right)^2 - \cos x \right) = 0$$

The equation of motion of pendulums

$$\frac{d^2x}{dt^2} + \sin x = 0$$

$\Rightarrow$

$$\frac{1}{2} \left(\frac{dx}{dt} \right)^2 - \cos x = \underline{\text{const.}}$$

energy integral
✓
• conservation law of mechanical energy

The equation of motion of pendulums: A special solution

$$x(0) = 0 \quad \dot{x}(0) = 2$$

$$\frac{1}{2} \left(\frac{dx}{dt} \right)^2 - \cos x = \text{const.}$$

$$= \frac{1}{2} \left(\underbrace{\frac{dx}{dt}(0)}_2 \right)^2 - \cos \underbrace{x(0)}_0 = \frac{1}{2} \times 2^2 - 1 = 1$$

($\because x(0) = 0, \quad \dot{x}(0) = 2$)

$\Rightarrow$

$$\left(\frac{dx}{dt} \right)^2 = 2(1 + \cos x) = 4 \cos^2 \frac{x}{2}$$

$$\boxed{\frac{dx}{dt} = 2 \cos \frac{x}{2}}$$

$\oplus$

$$\frac{dx}{dt}(0) = 2 > 0$$

$$x(0) = 0$$

The equation of motion of pendulums: A special solution

$$\frac{dx}{dt} = 2 \cos \frac{x}{2} \quad \Rightarrow \quad 1 = \frac{1}{2} \sec \frac{x}{2} \frac{dx}{dt} .$$

$$t = \int_0^t 1 dt = \frac{1}{2} \int_0^t \sec \frac{x(t)}{2} \frac{dx(t)}{dt} dt = \frac{1}{2} \underbrace{\int_{x(0)}^{x(t)} \sec \frac{x}{2} dx}$$

$$= \frac{1}{2} \ln \frac{1 + \tan \frac{x}{4}}{1 - \tan \frac{x}{4}}$$

$$\tan \frac{x}{4} = \frac{e^t - 1}{e^t + 1}$$

$$= \tanh \frac{t}{2}$$

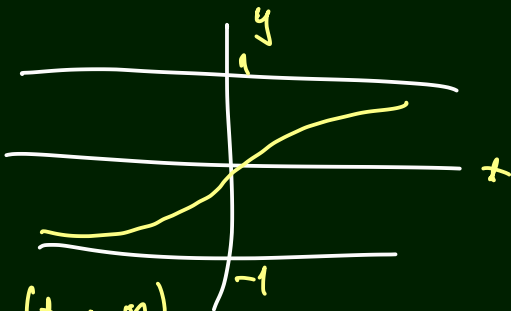

$$x(t) = 4 \tan^{-1} \tanh \frac{t}{2}$$

The equation of motion of pendulums: A special solution

$$x(t) = 4 \tan^{-1} \tanh \frac{t}{2}$$

↓
pseudosphere

$$y = \tanh \frac{t}{2}$$



$$\begin{array}{ll} x \rightarrow \pi & (t \rightarrow \infty) \\ x \rightarrow -\pi & (t \rightarrow -\infty) \end{array}$$

Exercise 2-3

linear differential eq.

Problem (Ex. 2-3)

Find an explicit expression of a space curve $\gamma(s)$ parametrized by the arc-length s , whose curvature κ and torsion τ satisfy

$$\kappa = \tau = \frac{1}{\sqrt{2(1+s^2)}}.$$

Strategy: Solve

$$\frac{d}{ds}\mathcal{F} = \mathcal{F} \begin{pmatrix} 0 & -\kappa & 0 \\ \kappa & 0 & -\tau \\ 0 & \tau & 0 \end{pmatrix}, \quad \mathcal{F}(0) = \text{id}$$

for $\mathcal{F}(s) = (\mathbf{e}(s), \mathbf{n}(s), \mathbf{b}(s))$.

Then the desired curve is obtained by

$$\gamma'(s) = \int_0^s \mathbf{e}(s) ds \quad \rightarrow$$

Frenet-Serret equation

$$k = \tau = \frac{1}{\sqrt{2}} \frac{1}{1-t^2} \quad 3 \times 3$$

$$\frac{d}{ds} \mathcal{F} = \mathcal{F} \begin{pmatrix} 0 & -\kappa & 0 \\ \kappa & 0 & -\tau \\ 0 & \tau & 0 \end{pmatrix} = \frac{1}{1+s^2} \mathcal{F} \Omega,$$

$$\Omega := \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

constant matrix

Change Variable $s = \tan t \Rightarrow$

$$\frac{d}{dt} \mathcal{F} = \mathcal{F} \Omega$$

const

With initial condition $\mathcal{F}(0) = \text{id}$,

$$\mathcal{F}(t) = \exp t\Omega = \text{id} + \sum_{k=1}^{\infty} \frac{t^k}{k!} \Omega^k$$

$$\frac{ds}{dt} = 1 + s^2$$

Cayley-Hamilton

$$\Omega^3 + \Omega = 0$$

Frenet-Serret equation

$$\mathcal{F}(t) = \exp t\Omega = \text{id} + \sum_{k=1}^{\infty} \frac{t^k}{k!} \Omega^k \quad \Omega := \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

Note:

$$\underline{\Omega^2} = \frac{1}{2} \begin{pmatrix} -1 & 0 & 1 \\ 0 & -2 & 0 \\ 1 & 0 & -1 \end{pmatrix}, \quad \underline{\Omega^3 = -\Omega}, \quad \underline{\Omega^4 = -\Omega^2}.$$

$\Rightarrow$

$$s = \omega t$$

$$\exp t\Omega = \begin{pmatrix} \frac{1}{2}(1 + \cos t) & * & * \\ \frac{1}{\sqrt{2}} \sin t & * & * \\ \frac{1}{2}(1 - \cos t) & * & * \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \left(1 + \frac{1}{\sqrt{1+s^2}} \right) & * & * \\ \frac{1}{\sqrt{2}} \frac{s}{\sqrt{1+s^2}} & * & * \\ \frac{1}{\sqrt{2}} \left(1 - \frac{1}{\sqrt{1+s^2}} \right) & * & * \end{pmatrix}$$

Frenet-Serret equation

$$\begin{aligned} e(s) = \gamma'(s) &= \begin{pmatrix} \frac{1}{\sqrt{2}} \left(1 + \frac{1}{\sqrt{1+s^2}} \right) \\ \frac{1}{\sqrt{2}} \frac{s}{\sqrt{1+s^2}} \\ \frac{1}{\sqrt{2}} \left(1 - \frac{1}{\sqrt{1+s^2}} \right) \end{pmatrix} , \\ \gamma(s) &= \begin{pmatrix} \frac{1}{2} \left(s + \log(s + \sqrt{1+s^2}) \right) \\ \frac{1}{\sqrt{2}} \sqrt{1+s^2} \\ \frac{1}{2} \left(s - \log(s + \sqrt{1+s^2}) \right) \end{pmatrix} . \end{aligned}$$

Frenet-Serret equation: an alternative solution

$$\frac{d}{dt} \left(\underbrace{e + b}_{\sqrt{2}} \right) = 0 \quad \therefore \underbrace{\kappa = \tau}_{\text{const}}$$

$$\checkmark \quad \frac{d}{ds} \mathcal{F} = \mathcal{F} \begin{pmatrix} 0 & -\kappa & 0 \\ \kappa & 0 & -\kappa \\ 0 & \kappa & 0 \end{pmatrix}$$

Set

$$\mathcal{G} = \mathcal{F} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix} \sqrt{2}$$

then

$$\boxed{\frac{d}{ds} \mathcal{G} = \mathcal{G} \Lambda}, \quad \Lambda := \frac{1}{1+s^2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$