

Advanced Topics in Geometry A1 (MTH.B405)

Integrability Conditions

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Integrability Conditions

$$\chi = \chi(u_1, \dots, u_m)$$

linear

$$\frac{\partial \chi}{\partial u^j} = \chi \Omega_j \quad (j = 1, \dots, m), \quad \chi(P_0) = \chi_0. \quad (*)$$

Proposition (Prop. 3.2)

If a matrix-valued C^∞ function $\chi: U \rightarrow \text{GL}(n, \mathbb{R})$ satisfies $(*)$, it holds that

$$\frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j$$

for each (j, k) with $1 \leq j < k \leq m$.

($n \times n$ real matrix)
 $\det \neq 0$

$X = X(u, v) : n \times n$ -matrix valued

$$\underline{\frac{\partial X}{\partial u} = X \Omega} \quad \frac{\partial X}{\partial v} = \underline{X \Lambda}$$

Prop 3.2 Ω & Λ : ^{Given} functions in (u, v)

If X is a solution, valued in $GL(n, \mathbb{R})$

$$\Rightarrow \frac{\partial \Omega}{\partial v} - \frac{\partial \Lambda}{\partial u} = \Omega \Lambda - \Lambda \Omega$$

☺ $\frac{\partial^2 X}{\partial v \partial u} = \underline{\frac{\partial X}{\partial v}} \Omega + X \frac{\partial \Omega}{\partial v} = X \Lambda \Omega + X \frac{\partial \Omega}{\partial v}$

$$\frac{\partial^2 X}{\partial v \partial u} = \frac{\partial X}{\partial v} \Omega + X \frac{\partial \Omega}{\partial v} = X \wedge \Omega + X \frac{\partial \Omega}{\partial v}$$

$$\frac{\partial^2 X}{\partial u \partial v} = \frac{\partial X}{\partial u} \wedge + X \frac{\partial \wedge}{\partial u} = X \Omega \wedge + X \frac{\partial \wedge}{\partial u}$$

$$\cancel{X} \left(\wedge \Omega + \frac{\partial \Omega}{\partial v} \right) = \cancel{X} \left(\Omega \wedge + \frac{\partial \wedge}{\partial u} \right)$$

(det X ≠ 0)

Integrability of Linear systems

$$\bullet \quad \frac{\partial X}{\partial u^j} = X \Omega_j \quad (j = 1, \dots, m), \quad X(P_0) = X_0. \quad (1)$$

$$\bullet \quad \frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j \quad (2)$$

Theorem (Thm. 3.5)

Disc, whole space : simply connected.

✓ Let $\Omega_j : \underbrace{U}_{\text{disc, whole space : simply connected}} \rightarrow M_n(\mathbb{R})$ ($j = 1, \dots, m$) be C^∞ -functions defined on a simply connected domain $U \subset \mathbb{R}^m$ satisfying (2). Then for each $P_0 \in U$ and $X_0 \in M_n(\mathbb{R})$, there exists the unique $n \times n$ -matrix valued function $X : U \rightarrow M_n(\mathbb{R})$ satisfying (1)

$U \subset \mathbb{R}^2$ simply connected domain (homeo. to disc)

• Ω, Λ : matrix valued functions defined on U C^∞

with $\Omega_\nu - \Lambda_\mu = \Omega \Lambda - \Lambda \Omega$ integrability conditions

• $P_0 \in U$, X_0 : a given matrix

$\Rightarrow \exists! X: U \rightarrow M_n(\mathbb{R})$: $n \times n$ matrices

$$\text{with } \left(\begin{array}{l} \frac{\partial X}{\partial u} = X \Omega \quad \frac{\partial X}{\partial v} = X \Lambda \\ X(P_0) = X_0 \end{array} \right)$$

Integrability Conditions

Lemma (Lem. 3.4)

Let $\Omega_j: U \rightarrow M_n(\mathbb{R})$ ($j = 1, \dots, m$) be C^∞ -maps defined on a domain $U \subset \mathbb{R}^m$ which satisfy

$$\frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j.$$

Then for each smooth map

$$\sigma: D \ni (t, w) \longmapsto \sigma(t, w) = (u^1(t, w), \dots, u^m(t, w)) \in U$$

defined on a domain $D \subset \mathbb{R}^2$, it holds that

$$\frac{\partial T}{\partial w} - \frac{\partial W}{\partial t} - TW + WT = 0,$$

where $T := \sum_{j=1}^m \tilde{\Omega}_j \frac{\partial u^j}{\partial t}$, $W := \sum_{j=1}^m \tilde{\Omega}_j \frac{\partial u^j}{\partial w}$, $(\tilde{\Omega}_j := \Omega_j \circ \sigma)$.

Integrability Conditions

$$\frac{\partial X}{\partial u^j} = X\Omega_j \quad (j = 1, \dots, m), \quad X(P_0) = X_0. \quad (*)$$

Lemma (Lem. 3.3)

Let $X: U \rightarrow M_n(\mathbb{R})$ be a C^∞ -map satisfying $(*)$. Then for each smooth path $\gamma: I \rightarrow U$ defined on an interval $I \subset \mathbb{R}$, $\hat{X} := X \circ \gamma: I \rightarrow M_n(\mathbb{R})$ satisfies the ordinary differential equation

$$\frac{d\hat{X}}{dt}(t) = \hat{X}(t)\Omega_\gamma(t) \quad \left(\Omega_\gamma(t) := \sum_{j=1}^n \Omega_j \circ \gamma(t) \frac{du^j}{dt}(t) \right)$$

on I , where $\gamma(t) = (u^1(t), \dots, u^m(t))$.

Proof of Theorem 2.5 (outline)

- ▶ Take $P \in U$, and a path $\gamma: [0, 1] \rightarrow U$ with $\gamma(0) = P_0$ and $\gamma(1) = P$.
- ▶ Solve the linear ODE as in Lemma 2.3 with initial condition $\hat{X}(0) = X_0$.
- ▶ Show the value $\hat{X}(1)$ does not depend on $\gamma \Leftarrow$ by Lem. 3.4
- ▶ Define $X(P) := \hat{X}(1)$.
- ▶ Show X is the desired solution.

U

$\hat{\hat{X}}$

$$\begin{aligned} X: U &\rightarrow M_n(\mathbb{R}) \\ X(P) &= \hat{X}(1) \\ &= \hat{\hat{X}}(1) \end{aligned}$$

P

terminal values
do not depend on
paths.

$$\gamma(t) = (u(t), v(t))$$

$$0 \leq t \leq 1$$

$$= \hat{X} \left(\Omega \frac{du}{dt} + \Lambda \frac{dv}{dt} \right)$$

$$\hat{X}(0) = P_0$$

ODE

$$(X(P_0) = X_0)$$

P₀

$$\hat{X}(t) (= X(u(t), v(t)))$$

$$\frac{d\hat{X}}{dt} = \frac{\partial X}{\partial u} \frac{du}{dt} + \frac{\partial X}{\partial v} \frac{dv}{dt}$$

$I = [0, 1]$
 U
 U : simply connected $\Rightarrow \exists \sigma: I \times I \rightarrow U$
 continuously deform from γ_0 to γ_1

Integrability conditions

Whitney.

$\sigma(t, w)$

γ_0

p_0

$\hat{\chi}(t, w)$

$$\left. \frac{\partial \hat{\chi}}{\partial w} \right|_{\substack{t=0 \\ t=1}} = 0$$

$$\sigma(t, 0) = \gamma_0(t)$$

$$\sigma(t, 1) = \gamma_1(t)$$

$$\sigma(0, w) = p_0$$

$$\sigma(1, w) = p$$

Application: Poincaré's lemma

Theorem (Poincaré's lemma)

If a differential 1-form

$$\omega = \sum_{j=1}^m \alpha_j(u^1, \dots, u^m) du^j$$

defined on a simply connected domain $U \subset \mathbb{R}^m$ is closed, that is, $d\omega = 0$ holds, then there exists a C^∞ -function f on U such that $df = \omega$. Such a function f is unique up to additive constants.

$$\alpha = a(u,v) du + b(u,v) dv$$

U : simpl. conn

$$d\alpha = (\underline{b_u} - \underline{a_v}) du \wedge dv = 0$$

$$\Rightarrow \exists f(u,v) \text{ s.t. } df = f_u du + f_v dv = \alpha$$

$$\bullet \left(\begin{array}{cc} \sigma_u = a \overset{\sigma a}{\sigma} & \sigma_v = b \overset{\sigma b}{\sigma} \\ \sigma(p_0) = 1 \end{array} \right) \quad \sigma: 1 \times 1\text{-matrix valued}$$

integrability $a_v - b_u = \cancel{ab} - \cancel{ba} = 0$

$$\exists \sigma: U \rightarrow \mathbb{R} \quad \bullet \quad \sigma > 0$$

$$\boxed{f := \int \sigma}$$

Application: Conjugation of harmonic functions

Theorem

Let $U \subset \mathbb{C} = \mathbb{R}^2$ be a simply connected domain and $\xi(u, v)$ a C^∞ -function harmonic on U . Then there exists a C^∞ harmonic function η on U such that $\xi(u, v) + i\eta(u, v)$ is holomorphic on U .

$$\Delta \xi = \xi_{uu} + \xi_{vv} = 0$$

$\Rightarrow$

$$\begin{cases} \eta_u = -\xi_v \\ \eta_v = \xi_u \end{cases}$$

① : conjugate of ξ

Cauchy-Riemann
integrability condition:
 $-\xi_{vv} = \xi_{uu} \quad \therefore \Delta \xi = 0$

Application: Conjugation of harmonic functions

Example

$$\xi(u, v) = e^u \cos v$$

$$\eta(u, v) = e^u \sin v$$

$$\left(\begin{aligned} \xi + i\eta &= e^u (\cos v + i \sin v) \\ &= e^{u + iv} \end{aligned} \right)$$

Exercise 3-1

Problem

Let

$$\xi_1(u, v) := \frac{u}{u^2 + v^2}, \quad \xi_2(u, v) := \log \sqrt{u^2 + v^2}$$

be a function defined on non-simply connected domain

$$U := \mathbb{R}^2 \setminus \{(0, 0)\}.$$

1. Show that both ξ_1 and ξ_2 are harmonic on U .
2. Verify that there exists a conjugate harmonic function η_1 of ξ_1 on U .
3. Prove that there exists no conjugate harmonic function η_2 of ξ_2 on U .

Exercise 3-2

$$\Omega_v - \Lambda_u = \Omega\Lambda - \Lambda\Omega$$

Problem

Consider a linear system of partial differential equations for 3×3 -matrix valued unknown X on a domain $U \subset \mathbb{R}^2$ as

$$\frac{\partial X}{\partial u} = X\Omega, \quad \frac{\partial X}{\partial v} = X\Lambda, \quad .$$
$$\left(\Omega := \begin{pmatrix} 0 & -\alpha & -h_1^1 \\ \alpha & 0 & -h_1^2 \\ h_1^1 & h_1^2 & 0 \end{pmatrix}, \quad \Lambda := \begin{pmatrix} 0 & -\beta & -h_2^1 \\ \beta & 0 & -h_2^2 \\ h_2^1 & h_2^2 & 0 \end{pmatrix} \right),$$

where (u, v) are the canonical coordinate system of $\mathbb{R}^2$, and α , β and h_j^i ($i, j = 1, 2$) are smooth functions defined on U . Write down the integrability conditions in terms of α , β and h_j^i .